# Multivariate distributions and measures of dependence between random variables* 

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## 1. Random variables

1.1 In general, economic theory specifies exact relations between economic variables. Even a superficial examination of economic data indicates it is not (almost never) possible to find such relationships in actual data. Instead, we have relations of the form:

$$
C_{t}=\alpha+\beta Y_{t}+\varepsilon_{t}
$$

where $\varepsilon_{t}$ can be interpreted as a "random variable".
1.2 Definition $A$ random variable (r.v.) $X$ is a variable whose behavior can be described by a "probability law". If $X$ takes its values in the real numbers, the probability law of $X$ can be described by a "distribution function":

$$
F_{X}(x)=\mathrm{P}[X \leq x]
$$

1.3 If $X$ is continuous, there is a "density function" $f_{X}(x)$ such that

$$
F_{X}(x)=\int_{-\infty}^{x} f_{X}(x) d x
$$

The mean and variance of $X$ are given by:

$$
\begin{array}{cc}
\mu_{X}=\mathrm{E}(X)=\int_{-\infty}^{+\infty} x d F_{X}(x) & \text { (general case) } \\
=\int_{-\infty}^{+\infty} x f_{X}(x) d x & \text { (continuous case) } \\
\mathrm{V}(X)=\sigma_{X}^{2}=\mathrm{E}\left[\left(X-\mu_{X}\right)^{2}\right]=\int_{-\infty}^{+\infty}\left(x-\mu_{X}\right)^{2} d F_{X}(x) \\
=\int_{-\infty}^{+\infty}\left(x-\mu_{X}\right)^{2} F_{X}(x) d x & \text { (general case) } \\
=\mathrm{E}\left(X^{2}\right)-[\mathrm{E}(X)]^{2} & \text { (continuous case) }
\end{array}
$$

1.4 It is easy to characterize relations between two non-random variables $x$ and $y$ :

$$
g(x, y)=0
$$

or (in certain cases)

$$
y=f(x) .
$$

How does one characterize the links or relations between random variables? The behavior of a pair $(X, Y)^{\prime}$ is described by a joint distribution function:

$$
F(x, y)=\mathrm{P}[X \leq x, Y \leq y]
$$

$$
=\int_{-\infty}^{y} \int_{-\infty}^{x} f(x, y) d x d y \quad \quad \text { (continuous case.) }
$$

We call $f(x, y)$ the joint density function of $(X, Y)^{\prime}$. More generally, if we consider $k$ v.a.'s $X_{1}, X_{2}, \ldots, X_{k}$, their behavior can be described through a $k$-dimensional distribution function:

$$
\begin{aligned}
& F\left(x_{1}, x_{2}, \ldots, x_{k}\right)=\mathrm{P}\left[X_{1} \leq x_{1}, X_{2} \leq x_{2}, \ldots, X_{k} \leq x_{k}\right] \\
= & \int_{-\infty}^{x_{k}} \cdots \int_{-\infty}^{x_{2}} \int_{-\infty}^{x_{1}} f\left(x_{1}, x_{2}, \ldots, x_{k}\right) d x_{1} d x_{2} \cdots d x_{k}
\end{aligned} \quad \text { (continuous case) } \quad \text { ) }
$$

where $f\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is the joint density function of $X_{1}, X_{2}, \ldots, X_{k}$.

## 2. Covariances and correlations

### 2.1. Covariance and correlation between two random variables

We often wish to have a simple measure of association between two random variables $X$ and $Y$. The notions of "covariance" and "correlation" provide such measures of association. Let $X$ and $Y$ be two $r$.v.'s with means $\mu_{X}$ and $\mu_{Y}$ and finite variances $\sigma_{X}^{2}$ and $\sigma_{Y}^{2}$. Below a.s. means "almost surely" (with probability 1).
2.1 Definition The covariance between $X$ and $Y$ is defined by

$$
\mathrm{C}(X, Y) \equiv \sigma_{X Y} \equiv \mathrm{E}\left[\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right] .
$$

2.2 Definition Suppose $\sigma_{X}^{2}>0$ and $\sigma_{Y}^{2}>0$. Then the correlation between $X$ and $Y$ is defined by

$$
\rho(X, Y) \equiv \rho_{X Y} \equiv \sigma_{X Y} / \sigma_{X} \sigma_{Y}
$$

When $\sigma_{X}^{2}=0$ or $\sigma_{Y}^{2}=0$, we set $\rho_{X Y}=0$.
2.3 Theorem The covariance and correlation between $X$ and $Y$ satisfy the following properties:
(a) $\sigma_{X Y}=\mathrm{E}(X Y)-\mathrm{E}(X) \mathrm{E}(Y)$;
(b) $\sigma_{X Y}=\sigma_{Y X}, \rho_{X Y}=\rho_{Y X}$;
(c) $\sigma_{X X}=\sigma_{X}^{2}, \rho_{X X}=1$;
(d) $\sigma_{X Y}^{2} \leq \sigma_{X}^{2} \sigma_{Y}^{2}$;
(Cauchy-Schwarz inequality)
(e) $-1 \leq \rho_{X Y} \leq 1$;
(f) $X$ and $Y$ are independent $\Rightarrow \sigma_{X Y}=0 \Rightarrow \rho_{X Y}=0$;
(g) if $\sigma_{X}^{2} \neq 0$ and $\sigma_{Y}^{2} \neq 0$,

$$
\rho_{X Y}^{2}=1 \Leftrightarrow[\exists \text { two constants } a \text { and } b \text { such that } a \neq 0 \text { and } Y=a X+b \text { a.s. }]
$$

## Proof (a)

$$
\begin{aligned}
\sigma_{X Y} & =\mathrm{E}\left[\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right] \\
& =\mathrm{E}\left[X Y-\mu_{X} Y-X \mu_{Y}+\mu_{X} \mu_{Y}\right] \\
& =\mathrm{E}(X Y)-\mu_{X} \mathrm{E}(Y)-\mathrm{E}(X) \mu_{Y}+\mu_{X} \mu_{Y} \\
& =\mathrm{E}(X Y)-\mu_{X} \mu_{Y}-\mu_{X} \mu_{Y}+\mu_{X} \mu_{y} \\
& =\mathrm{E}(X Y)-\mathrm{E}(X) \mathrm{E}(Y)
\end{aligned}
$$

(b) et (c) are immediate. To get (d), we observe that

$$
\begin{gathered}
\mathrm{E}\left\{\left[Y-\mu_{Y}-\lambda\left(X-\mu_{X}\right)\right]^{2}\right\}=\mathrm{E}\left\{\left[\left(Y-\mu_{Y}\right)-\lambda\left(X-\mu_{X}\right)\right]^{2}\right\} \\
\mathrm{E} \mathrm{E}\left\{\left(Y-\mu_{Y}\right)^{2}-2 \lambda\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)+\lambda^{2}\left(X-\mu_{X}\right)^{2}\right\} \\
=\sigma_{Y}^{2}-2 \lambda \sigma_{X Y}+\lambda^{2} \sigma_{X}^{2} \geq 0
\end{gathered}
$$

for any arbitrary constant $\lambda$. In other words, the second-order polynomial $g(\lambda)=\sigma_{Y}^{2}-2 \lambda \sigma_{X Y}+$ $\lambda^{2} \sigma_{X}^{2}$ cannot take negative values. This can happen only if the equation

$$
\begin{equation*}
\lambda^{2} \sigma_{X}^{2}-2 \lambda \sigma_{X Y}+\sigma_{Y}^{2}=0 \tag{2.1}
\end{equation*}
$$

does not have two distinct real roots, i.e. the roots are either complex or identical. The roots of equation (2.1). are given by

$$
\lambda=\frac{2 \sigma_{X Y} \pm \sqrt{4 \sigma_{X Y}^{2}-4 \sigma_{X}^{2} \sigma_{Y}^{2}}}{2 \sigma_{X}^{2}}=\frac{\sigma_{X Y} \pm \sqrt{\sigma_{X Y}^{2}-\sigma_{X}^{2} \sigma_{Y}^{2}}}{\sigma_{X}^{2}}
$$

Distinct real roots are excluded when $\sigma_{X Y}^{2}-\sigma_{X}^{2} \sigma_{Y}^{2} \leq 0$, hence

$$
\sigma_{X Y}^{2} \leq \sigma_{X}^{2} \sigma_{Y}^{2}
$$

(e)

$$
\begin{aligned}
\sigma_{X Y}^{2} \leq \sigma_{X}^{2} \sigma_{Y}^{2} & \Rightarrow-\sigma_{X} \sigma_{Y} \leq \sigma_{X Y} \leq \sigma_{X} \sigma_{Y} \\
& \Rightarrow-1 \leq \rho_{X Y} \leq 1
\end{aligned}
$$

(f)

$$
\begin{aligned}
\sigma_{X Y} & =\mathrm{E}\left\{\left(X-\mu_{X}\right)\left(Y-\mu_{Y}\right)\right\}=\mathrm{E}\left(X-\mu_{X}\right) \mathrm{E}\left(Y-\mu_{Y}\right) \\
& =\left[\mathrm{E}(X)-\mu_{X}\right]\left[\mathrm{E}(Y)-\mu_{Y}\right]=0, \\
\rho_{X Y} & =\sigma_{X Y} / \sigma_{X} \sigma_{Y}=0 .
\end{aligned}
$$

Note the reverse implication does not hold in general, i.e.,

$$
\rho_{X Y}=0 \neq>X \text { and } Y \text { are independent }
$$

(g) 1) Necessity of the condition. If $Y=a X+b$, then

$$
\mathrm{E}(Y)=a \mathrm{E}(X)+b=a \mu_{X}+b, \sigma_{Y}^{2}=a^{2} \sigma_{X}^{2},
$$

and

$$
\sigma_{X Y}=\mathrm{E}\left[\left(Y-\mu_{Y}\right)\left(X-\mu_{X}\right)\right]=\mathrm{E}\left[a\left(X-\mu_{X}\right)\left(X-\mu_{X}\right)\right]=a \sigma_{X}^{2} .
$$

Consequently,

$$
\rho_{X Y}^{2}=\frac{a^{2} \sigma_{X}^{4}}{a^{2} \sigma_{X}^{2} \sigma_{X}^{2}}=1 .
$$

2) Sufficiency of the condition. If $\rho_{X Y}^{2}=1$, then

$$
\sigma_{X Y}^{2}-\sigma_{X}^{2} \sigma_{Y}^{2}=0
$$

In this case, the equation

$$
\mathrm{E}\left\{\left[\left(Y-\mu_{Y}\right)-\lambda\left(X-\mu_{X}\right)\right]^{2}\right\}=\sigma_{Y}^{2}-2 \lambda \sigma_{X Y}+\lambda^{2} \sigma_{X}^{2}=0
$$

has one and only one root

$$
\lambda=\frac{2 \sigma_{X Y}}{2 \sigma_{X}^{2}}=\sigma_{X Y} / \sigma_{X}^{2},
$$

so that

$$
\mathrm{E}\left\{\left[\left(Y-\mu_{Y}\right)-\frac{\sigma_{X Y}}{\sigma_{X}^{2}}\left(X-\mu_{X}\right)\right]^{2}\right\}=0
$$

and

$$
\mathrm{P}\left[\left(Y-\mu_{Y}\right)-\frac{\sigma_{X Y}}{\sigma_{X}^{2}}\left(X-\mu_{X}\right)=0\right]=\mathrm{P}\left[Y=\frac{\sigma_{X Y}}{\sigma_{X}^{2}} X+\left(\mu_{Y}-\frac{\sigma_{X Y}}{\sigma_{X}^{2}} \mu_{X}\right)\right]=1
$$

We can thus write:

$$
Y=a X+b \text { with probability } 1
$$

where $a=\sigma_{X Y} / \sigma_{X}^{2}$ and $b=\mu_{Y}-\frac{\sigma_{X Y}}{\sigma_{y}^{2}} \mu_{X}$.

### 2.2. Covariances and correlations between $k$ random variables

Consider now kr.v.'s $X_{1}, X_{2}, \ldots, X_{k}$ such that

$$
\begin{aligned}
\mathrm{E}\left(X_{i}\right) & =\mu_{i}, i=1, \ldots, k \\
\mathrm{C}\left(X_{i}, X_{j}\right) & =\sigma_{i j}, i, j=1, \ldots, k
\end{aligned}
$$

We often wish to compute the mean and variance of a linear combination of $X_{1}, \ldots, X_{k}$ :

$$
\Sigma_{i=1}^{k} a_{i} X_{i}=a_{1} X_{1}+a_{2} X_{2}+\cdots+a_{k} X_{k} .
$$

It is easily verified that

$$
\mathrm{E}\left[\Sigma_{i=1}^{k} a_{i} X_{i}\right]=\Sigma_{i=1}^{k} a_{i} \mu_{i}
$$

and

$$
\begin{aligned}
\mathrm{V}\left[\Sigma_{i=1}^{k} a_{i} X_{i}\right] & =\mathrm{E}\left\{\left[\Sigma_{i=1}^{k} a_{i}\left(X_{i}-\mu_{i}\right)\right]\left[\Sigma_{j=1}^{k} a_{j}\left(X_{j}-\mu_{j}\right)\right]\right\} \\
& =\Sigma_{i=1}^{k} \Sigma_{j=1}^{k} a_{i} a_{j} \sigma_{i j} .
\end{aligned}
$$

Since such formulae may often become cumbersome, it will be convenient to use vector and matrix notation

We define a random vector $\mathbf{X}$ and its mean value $\mathrm{E}(\mathbf{X})$ by:

$$
\mathbf{X}=\left(\begin{array}{c}
X_{1} \\
\vdots \\
X_{k}
\end{array}\right), \mathrm{E}(\mathbf{X})=\left(\begin{array}{c}
\mathrm{E}\left(X_{1}\right) \\
\vdots \\
\mathrm{E}\left(X_{k}\right)
\end{array}\right)=\left(\begin{array}{c}
\mu_{1} \\
\vdots \\
\mu_{k}
\end{array}\right) \equiv \mu_{X} .
$$

Similarly, we define a random matrix $M$ and its mean value $\mathrm{E}(M)$ by:

$$
M=\left[\begin{array}{cccc}
X_{11} & X_{12} & \ldots & X_{1 n} \\
X_{21} & X_{22} & \ldots & X_{2 n} \\
\vdots & \vdots & & \vdots \\
X_{m 1} & X_{m 2} & \ldots & X_{m n}
\end{array}\right], \mathrm{E}(M)=\left[\begin{array}{cccc}
\mathrm{E}\left(X_{11}\right) & \mathrm{E}\left(X_{12}\right) & \ldots & \mathrm{E}\left(X_{1 n}\right) \\
\mathrm{E}\left(X_{21}\right) & \mathrm{E}\left(X_{22}\right) & \ldots & \mathrm{E}\left(X_{2 n}\right) \\
\vdots & \vdots & & \vdots \\
\mathrm{E}\left(X_{m 1}\right) & \mathrm{E}\left(X_{m 2}\right) & \ldots & \mathrm{E}\left(X_{m n}\right)
\end{array}\right]
$$

where the $X_{i j}$ are r.v.'s. To a random vector $\mathbf{X}$, we can associate a covariance matrix $\vee(\mathbf{X})$ :

$$
\begin{aligned}
\mathrm{V}(\mathbf{X}) & =\mathrm{E}\left\{[\mathbf{X}-\mathrm{E}(\mathbf{X})][\mathbf{X}-\mathrm{E}(\mathbf{X})]^{\prime}\right\}=\mathrm{E}\left\{\left[\mathbf{X}-\mu_{X}\right]\left[\mathbf{X}-\mu_{X}\right]^{\prime}\right\} \\
& =\mathrm{E}\left\{\left[\begin{array}{cccc}
\left(X_{1}-\mu_{1}\right)\left(X_{1}-\mu_{1}\right) & \left(X_{1}-\mu_{1}\right)\left(X_{2}-\mu_{2}\right) & \ldots & \left(X_{1}-\mu_{1}\right)\left(X_{k}-\mu_{k}\right) \\
\vdots & \vdots & \vdots \\
\left(X_{k}-\mu_{k}\right)\left(X_{1}-\mu_{1}\right) & \left(X_{k}-\mu_{k}\right)\left(X_{2}-\mu_{2}\right) & \ldots & \left(X_{k}-\mu_{k}\right)\left(X_{k}-\mu_{k}\right)
\end{array}\right]\right\} \\
& =\left[\begin{array}{cccc}
\sigma_{11} & \sigma_{12} & \ldots & \sigma_{1 k} \\
\vdots & \vdots & \vdots \\
\sigma_{k 1} & \sigma_{k 2} & \ldots & \sigma_{k k}
\end{array}\right]=\Sigma .
\end{aligned}
$$

If $\mathbf{a}=\left(a_{1}, \ldots, a_{k}\right)^{\prime}$, we see that:

$$
\Sigma_{i=1}^{k} a_{i} X_{i}=\mathbf{a}^{\prime} \mathbf{X} .
$$

Basic properties of $\mathrm{E}(\mathbf{X})$ and $\mathrm{V}(\mathbf{X})$ are summarized by the following proposition.
2.4 Proposition Let $\mathbf{X}=\left(X_{1}, \ldots, X_{k}\right)^{\prime}$ a $k \times 1$ random vector, $\alpha$ a scalar, a and $\mathbf{b}$ fixed $k \times 1$ vectors, and $A$ a fixed $g \times k$ matrix. Then, provided the moments considered are finite, we have the following properties:
(a) $\mathrm{E}(\mathbf{X}+\mathbf{a})=\mathrm{E}(\mathbf{X})+\mathbf{a}$;
(b) $\mathrm{E}(\alpha \mathbf{X})=\alpha \mathrm{E}(\mathbf{X})$;
(c) $\mathrm{E}\left(\mathbf{a}^{\prime} \mathbf{X}\right)=\mathbf{a}^{\prime} \mathrm{E}(\mathbf{X}), \mathrm{E}(A \mathbf{X})=A \mathrm{E}(\mathbf{X})$;
(d) $\mathrm{V}(\mathbf{X}+\mathbf{a})=\mathrm{V}(\mathbf{X})$;
(e) $\vee(\alpha \mathbf{X})=\alpha^{2} \vee(\mathbf{X})$;
(f) $\vee\left(\mathbf{a}^{\prime} \mathbf{X}\right)=\mathbf{a}^{\prime} \vee(\mathbf{X}) \mathbf{a}, \vee(A \mathbf{X})=A \bigvee(\mathbf{X}) A^{\prime} ;$
$(g) \mathrm{C}\left(\mathbf{a}^{\prime} \mathbf{X}, \mathbf{b}^{\prime} \mathbf{X}\right)=\mathbf{a}^{\prime} \vee(\mathbf{X}) \mathbf{b}=\mathbf{b}^{\prime} \bigvee(\mathbf{X}) \mathbf{a}$.
2.5 Theorem Let $\mathbf{X}=\left(X_{1}, \ldots, X_{k}\right)^{\prime}$ be a random vector with covariance matrix $\vee(\mathbf{X})=\Sigma$. Then we have the following properties:
(a) $\Sigma^{\prime}=\Sigma$;
(b) $\Sigma$ is a positive semidefinite matrix;
(c) $0 \leq|\Sigma| \leq \sigma_{1}^{2} \sigma_{2}^{2} \ldots \sigma_{k}^{2}$ where $\sigma_{i}^{2}=\mathrm{V}\left(X_{i}\right), i=1, \ldots, k$;
(d) $|\Sigma|=0 \Leftrightarrow$ there is at least one linear relation between the r.v.'s $X_{1}, \ldots, X_{k}$, i.e., we can find constants $a_{1}, \ldots, a_{k}, b$ not all equal to zero such that $a_{1} X_{1}+\cdots+a_{k} X_{k}=b$ with probability 1 ;
(e) $\operatorname{rank}(\Sigma)=r<k \Leftrightarrow \mathbf{X}$ can be expressed in the form

$$
\mathbf{X}=B \mathbf{Y}+\mathbf{c}
$$

where $\mathbf{Y}$ is a random vector of dimension $r$ whose covariance matrix is $I_{r}, B$ is a $k \times r$ matrix of rank $r$, and $\mathbf{c}$ is a $k \times 1$ constant vector.
2.6 Remark We call the determinant $|\Sigma|$ the generalized variance of $\mathbf{X}$.
2.7 Definition If we consider two random vectors $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ with dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively, the covariance matrix between $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ is defined by:

$$
\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\mathrm{E}\left\{\left[\mathbf{X}_{1}-\mathrm{E}\left(\mathbf{X}_{1}\right)\right]\left[\mathbf{X}_{2}-\mathrm{E}\left(\mathbf{X}_{2}\right)\right]^{\prime}\right\}
$$

The following proposition summarizes some basic properties of $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)$.
2.8 Proposition Let $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ two random vectors of dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively. Then, provided the moments considered are finite we have the following properties:
(a) $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\mathrm{E}\left[\mathbf{X}_{1} \mathbf{X}_{2}^{\prime}\right]-\mathrm{E}\left(\mathbf{X}_{1}\right) \mathrm{E}\left(\mathbf{X}_{2}\right)^{\prime}$;
(b) $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\mathrm{C}\left(\mathbf{X}_{2}, \mathbf{X}_{1}\right)^{\prime}$;
(c) $\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{1}\right)=\mathrm{V}\left(\mathbf{X}_{1}\right), \mathrm{C}\left(\mathbf{X}_{2}, \mathbf{X}_{2}\right)=\mathrm{V}\left(\mathbf{X}_{2}\right)$;
(d) if $\mathbf{a}$ and $\mathbf{b}$ are fixed vectors of dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively,

$$
\mathrm{C}\left(\mathbf{X}_{1}+\mathbf{a}, \mathbf{X}_{2}+\mathbf{b}\right)=\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) ;
$$

(e) if $\alpha$ and $\beta$ are two scalar constants,

$$
\mathrm{C}\left(\alpha \mathbf{X}_{1}, \beta \mathbf{X}_{2}\right)=\alpha \beta \mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) ;
$$

$(f)$ if $\mathbf{a}$ and $\mathbf{b}$ are fixed $k_{1} \times 1$ and $k_{2} \times 1$ vectors,

$$
\mathrm{C}\left(\mathbf{a}^{\prime} \mathbf{X}_{1}, \mathbf{b}^{\prime} \mathbf{X}_{2}\right)=\mathbf{a}^{\prime} \mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) \mathbf{b} ;
$$

$(g)$ if $A$ and $B$ are fixed matrices matrices with dimensions $g_{1} \times k_{1}$ and $g_{2} \times k_{2}$ respectively,

$$
\mathrm{C}\left(A \mathbf{X}_{1}, B \mathbf{X}_{2}\right)=\mathbf{A C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) \mathbf{B}^{\prime} ;
$$

(h) if $k_{1}=k_{2}$ and $\mathbf{X}_{3}$ is a $k \times 1$ random vector,

$$
\mathrm{C}\left(\mathbf{x}_{1}+\mathbf{X}_{2}, \mathbf{x}_{3}\right)=\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{x}_{3}\right)+\mathrm{C}\left(\mathbf{X}_{2}, \mathbf{x}_{3}\right) ;
$$

(i) if $k_{1}=k_{2}$,

$$
\begin{aligned}
\mathrm{V}\left(\mathbf{x}_{1}+\mathbf{X}_{2}\right) & =\mathrm{V}\left(\mathbf{x}_{1}\right)+\mathrm{V}\left(\mathbf{X}_{2}\right)+\mathrm{C}\left(\mathbf{x}_{1}, \mathbf{x}_{2}\right)+\mathrm{C}\left(\mathbf{x}_{2}, \mathbf{x}_{1}\right), \\
\mathrm{V}\left(\mathbf{x}_{1}-\mathbf{X}_{2}\right) & =\mathrm{V}\left(\mathbf{x}_{1}\right)+\mathrm{V}\left(\mathbf{X}_{2}\right)-\mathrm{C}\left(\mathbf{x}_{1}, \mathbf{x}_{2}\right)-\mathrm{C}\left(\mathbf{x}_{2}, \mathbf{x}_{1}\right) .
\end{aligned}
$$

## 3. Multinormal distribution

Consider two random vectors $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ with dimensions $k_{1} \times 1$ and $k_{2} \times 1$ respectively. If $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ are independent, then

$$
\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right) \equiv \mathrm{E}\left[\left(\mathbf{X}_{1}-\mu_{X_{1}}\right)\left(\mathbf{x}_{2}-\mu_{X_{2}}\right)^{\prime}\right]=0
$$

The reverse implication is not true in general, except in special cases. One such case is the one where the random vector $\mathbf{X}=\left(\mathbf{X}_{1}^{\prime}, \mathbf{X}_{2}^{\prime}\right)^{\prime}$ follows a multinormal distribution.
3.1 Definition We say that the $k \times 1$ random vector $\mathbf{X}$ follows a multinormal distribution with mean
$\mu$ and covariance matrix $\Sigma$, denoted $\mathbf{X} \sim N_{k}[\mu, \Sigma]$, if the characteristic function of $\mathbf{X}$ has the form:

$$
\mathrm{E}\left[e^{i \mathbf{t}^{\prime} \mathbf{X}}\right]=e^{i \mu^{\prime} \mathbf{t}-\frac{1}{2} \mathbf{t}^{\prime} \Sigma \mathbf{t}}, \quad \mathbf{t} \in \mathscr{R}^{k}, i=\sqrt{-1}
$$

3.2 When $|\Sigma| \neq 0$, the vector $\mathbf{X}$ has a density function of the form:

$$
f(\mathbf{x})=\frac{1}{(2 \pi)^{k / 2}|\Sigma|^{\frac{1}{2}}} \exp \left[-\frac{1}{2}(\mathbf{x}-\mu)^{\prime} \Sigma^{-1}(\mathbf{x}-\mu)\right]
$$

If $k=1$, then $\Sigma=\sigma^{2}$ and

$$
f(x)=\frac{1}{\sqrt{2 \pi} \sigma} \exp \left[-\frac{1}{2}(x-\mu) \frac{1}{\sigma^{2}}(x-\mu)\right]=\frac{1}{\sqrt{2 \pi} \sigma} \exp \left[-\frac{1}{2} \frac{(x-\mu)^{2}}{\sigma^{2}}\right] .
$$

Some important properties of the multinormal distribution are summarized in the following theorem.
3.3 Theorem If $\mathbf{X} \sim N_{k}[\mu, \Sigma]$, then
(a) $\mathbf{X}+\mathbf{c} \sim N_{k}[\mu+\mathbf{c}, \Sigma]$, for any fixed $k \times 1$ vector $\mathbf{c}$;
(b) $\mathbf{a}^{\prime} \mathbf{X} \sim N_{1}\left[\mathbf{a}^{\prime} \mu, \mathbf{a}^{\prime} \Sigma \mathbf{a}\right]$, for any fixed $k \times 1$ vector $\mathbf{a}$;
(c) $A \mathbf{X} \sim N_{g}\left[A \mu, A \Sigma A^{\prime}\right]$, for any fixed $g \times k$ matrix $A$;
(d) if

$$
\mathbf{X}=\binom{\mathbf{X}_{1}}{\mathbf{X}_{2}} \sim N_{k}\left[\binom{\mu_{1}}{\mu_{2}},\left(\begin{array}{ll}
\Sigma_{11} & \Sigma_{12} \\
\Sigma_{21} & \Sigma_{22}
\end{array}\right)\right],
$$

where $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ are vectors of dimensions $k_{1} \times 1$ and $k_{2} \times 1$,

$$
\begin{aligned}
\mu_{1} & =\mathrm{E}\left(\mathbf{X}_{1}\right), \mu_{2}=\mathrm{E}\left(\mathbf{X}_{2}\right), \Sigma_{11}=\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{1}\right), \Sigma_{22}=\mathrm{C}\left(\mathbf{X}_{2}, \mathbf{X}_{2}\right), \\
\Sigma_{12} & =\mathrm{C}\left(\mathbf{X}_{1}, \mathbf{X}_{2}\right)=\Sigma_{21}^{\prime},
\end{aligned}
$$

then
(i) $\mathbf{X}_{1} \sim N_{k_{1}}\left[\mu_{1}, \Sigma_{11}\right], \mathbf{X}_{2} \sim N_{k_{2}}\left[\mu_{2}, \Sigma_{22}\right]$;
(ii) $\mathbf{X}_{1}$ and $\mathbf{X}_{2}$ are independent $\Leftrightarrow \Sigma_{12}=0$;
(iii) the conditional distribution of $\mathbf{X}_{2}$ given $\mathbf{X}_{1}$ is normal with mean and et variance

$$
\begin{aligned}
\mathrm{E}\left[\mathbf{X}_{2} \mid \mathbf{X}_{1}\right] & =\mu_{2}+\Sigma_{21} \Sigma_{11}^{-1}\left(\mathbf{X}_{1}-\mu_{1}\right), \\
\mathrm{V}\left[\mathbf{X}_{2} \mid \mathbf{X}_{1}\right] & =\Sigma_{22}-\Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12},
\end{aligned}
$$

i.e.

$$
\mathbf{X}_{2} \mid \mathbf{X}_{1} \sim N_{k_{2}}\left[\mu_{2}+\Sigma_{21} \Sigma_{11}^{-1}\left(\mathbf{X}_{1}-\mu_{1}\right), \Sigma_{22}-\Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12}\right]
$$

3.4 Theorem If $\mathbf{X} \sim N_{k}[\mu, \Sigma]$ with $|\Sigma| \neq 0$, then

$$
(\mathbf{X}-\mu)^{\prime} \Sigma^{-1}(\mathbf{X}-\mu) \sim \chi^{2}(k)
$$

Proof Since $\Sigma$ is a positive definite matrix $(|\Sigma| \neq 0)$, there exists a nonsingular matrix $P$ such that

$$
P \Sigma P^{\prime}=I_{k}
$$

hence

$$
\begin{aligned}
\Sigma & =P^{-1}\left(P^{\prime}\right)^{-1}=\left(P^{\prime} P\right)^{-1} \\
\Sigma^{-1} & =P^{\prime} P
\end{aligned}
$$

Consequently,

$$
\begin{aligned}
(\mathbf{X}-\mu)^{\prime} \Sigma^{-1}(\mathbf{X}-\mu) & =(\mathbf{X}-\mu)^{\prime} P^{\prime} P(\mathbf{X}-\mu) \\
& =[P(\mathbf{X}-\mu)]^{\prime}[P(\mathbf{X}-\mu)]=\mathbf{v}^{\prime} \mathbf{v}=\Sigma_{i=1}^{k} v_{i}^{2}
\end{aligned}
$$

where

$$
\mathbf{v} \equiv P[\mathbf{X}-\mu]=\left(v_{1}, v_{2}, \ldots, v_{k}\right)^{\prime} .
$$

Since $\mathbf{X} \sim N[\mu, \Sigma]$, we have $\mathbf{X}-\mu \sim N[\mathbf{0}, \Sigma]$, hence

$$
P[\mathbf{X}-\mu] \sim N\left[\mathbf{0}, P \Sigma P^{\prime}\right],
$$

and

$$
\mathbf{v}=P[\mathbf{X}-\mu] \sim N\left[\mathbf{0}, I_{k}\right] .
$$

Thus $v_{1}, \ldots, v_{k}$ are i.i.d. $N[0,1]$ and $(\mathbf{X}-\mu)^{\prime} \Sigma^{-1}(\mathbf{X}-\mu)=\Sigma_{i=1}^{k} v_{i}^{2} \sim \chi^{2}(k)$.


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